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SACLANTCEN'S SHIPBOARD WINCHES AND LAUNCH-AND-RECOVERY DEVICES. (U)

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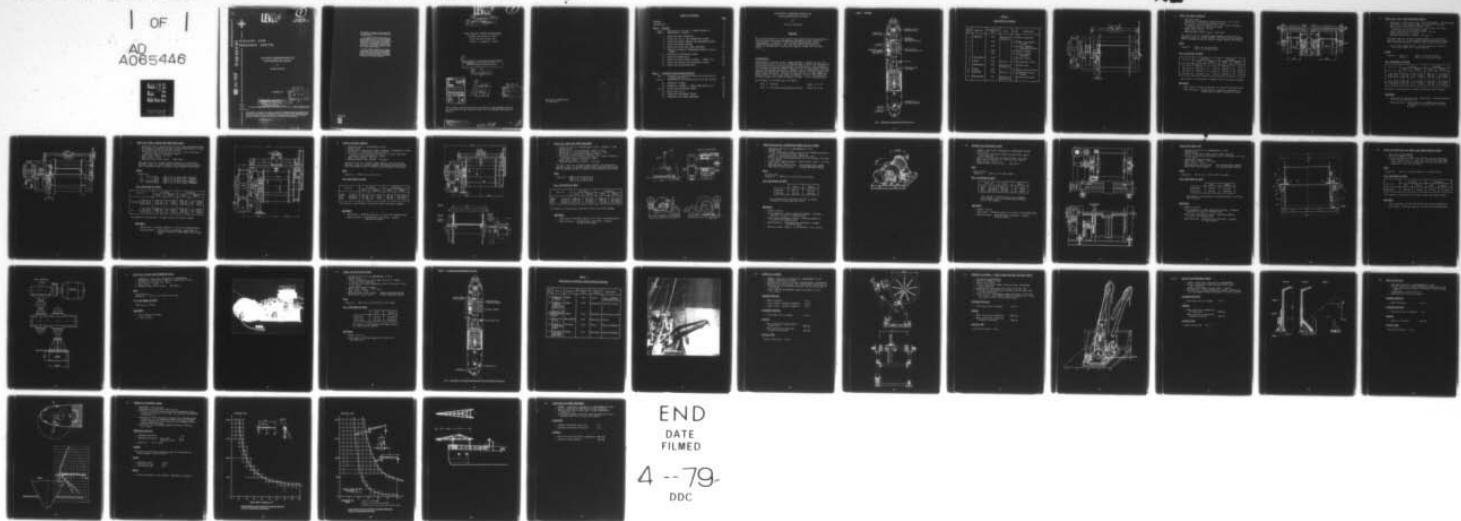
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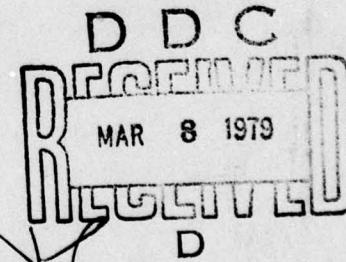
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SACLANTCEN'S SHIPBOARD WINCHES AND
LAUNCH-AND-RECOVERY DEVICES

by

VITTORIO MANZOTTI

15 MARCH 1976



VIALE SAN BARTOLOMEO 400
I - 19026 - LA SPEZIA, ITALY

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NORTH ATLANTIC TREATY ORGANIZATION

SACLANT ASW Research Centre

Viale San Bartolomeo 400

I 19026 - La Spezia, Italy

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LAUNCH-AND-RECOVERY DEVICES.

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SACLANTCEN'S SHIPBOARD WINCHES AND LAUNCH-AND-RECOVERY DEVICES

by

Vittorio Manzotti

ABSTRACT

The characteristics of all winches and launch-and-recovery devices, some of which have been designed or modified to meet specific requirements, available at the SACLANT ASW Research Centre (SACLANTCEN) are listed. The work described represents the effort of SACLANTCEN's Engineering Support Group over the past years.

INTRODUCTION

SACLANTCEN's research vessel, MARIA PAOLINA G. (MPG) and its work boat (T-boat) are, or can be, equipped with a variety of winches and launch-and-recovery devices for use in experiments. This document is provided to acquaint SACLANTCEN staff and collaborating personnel with the facilities available. Tables 1 and 2 respectively list the winches and launch-and-recovery devices and give a brief summary of their characteristics. Details of each one are provided under the number given in the first column of Tables 1 and 2. The positions of these items on the MPG are shown in Figs. 1 and 2 respectively.

The document is divided into two parts:

Part 1: Winches pages 2 to 25

Part 2: Launching-and-Recovery Devices pages 26 to 41

PART 1 - WINCHES

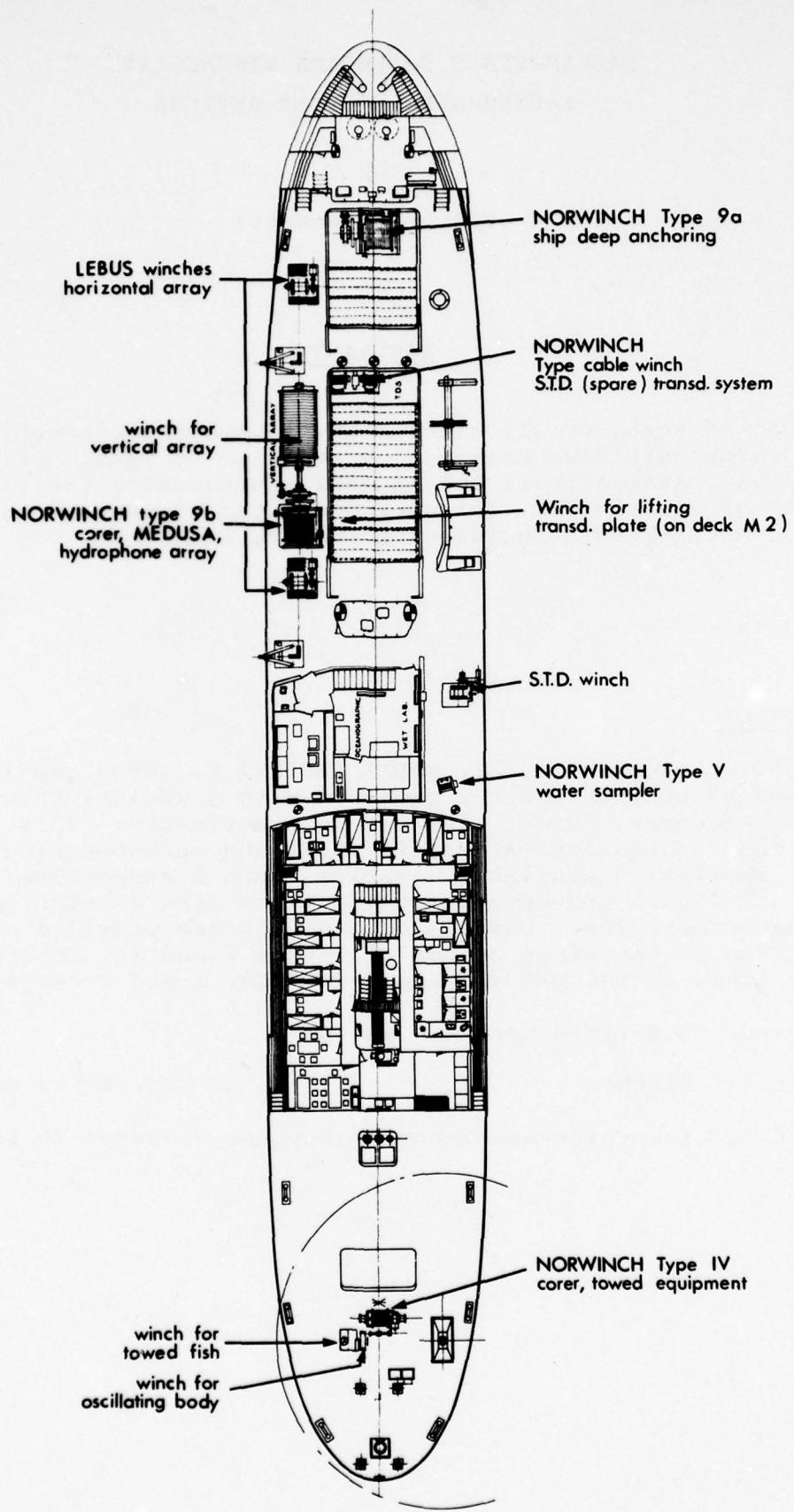
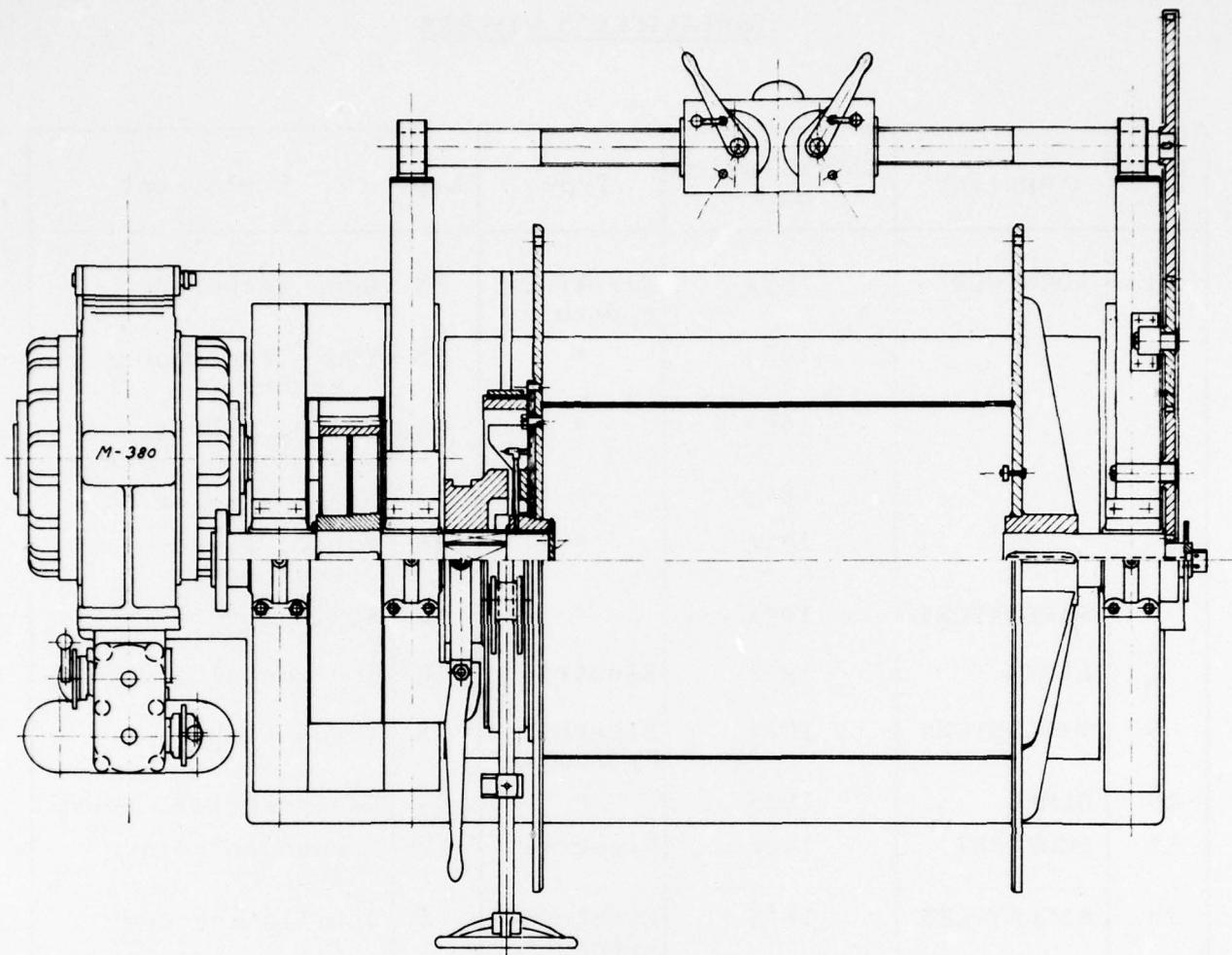


FIG. 1 POSITIONS OF WINCHES ON MARIA PAOLINA G.

TABLE 1
SACLANTCEN'S WINCHES

Item No.	Supplier	Installation date	Type	h.p.	Employment
1	NORWINCH	1974	Electric-hydraulic	85	Deep anchoring
2	"	1964	"	38	TDS - Transducer system
3	"	1968	"	85	Corer, MEDUSA, Hydrophone array
4	"	1964	"	25	Water sampler
5	"	1964	"	48	Corer, Towed equipment
6	SACLANTCEN	1974	"	12	S.T.D. probe
7	LEBUS	1974	Electric	10	Horizontal array
8	SACLANTCEN	1974	Electric-hydraulic	5	Towed fish
10	OLMEC	1968	"	85	Deep vertical array
11	SGORBINI	1964	Electric	12	Transducer plate system
12	SACLANTCEN	1975	Electric-hydraulic	2	Oscillating body



1. WINCH FOR DEEP ANCHORING

- Norwinch type 9
- Permanently installed on MPG (hatch No. 1) in 1974
- Driven by a type M-540 hydraulic motor
- The power unit utilizes a 85 h.p. a.c. motor driving a Norwinch type P 37 hydraulic pump
- Shaft motor power: 60 h.p.
- Gear ratio: 1:2.2
- Maximum shaft drum torque: 2900 kg.m

The motor has two variable speed ranges, one giving the maximum torque at normal speeds (1st step) and one giving 40% of maximum torque at double normal speeds (2nd step).

DRUM

Capacity: 7000 m of 12 mm Ø wire
3100 m of 19 mm Ø wire

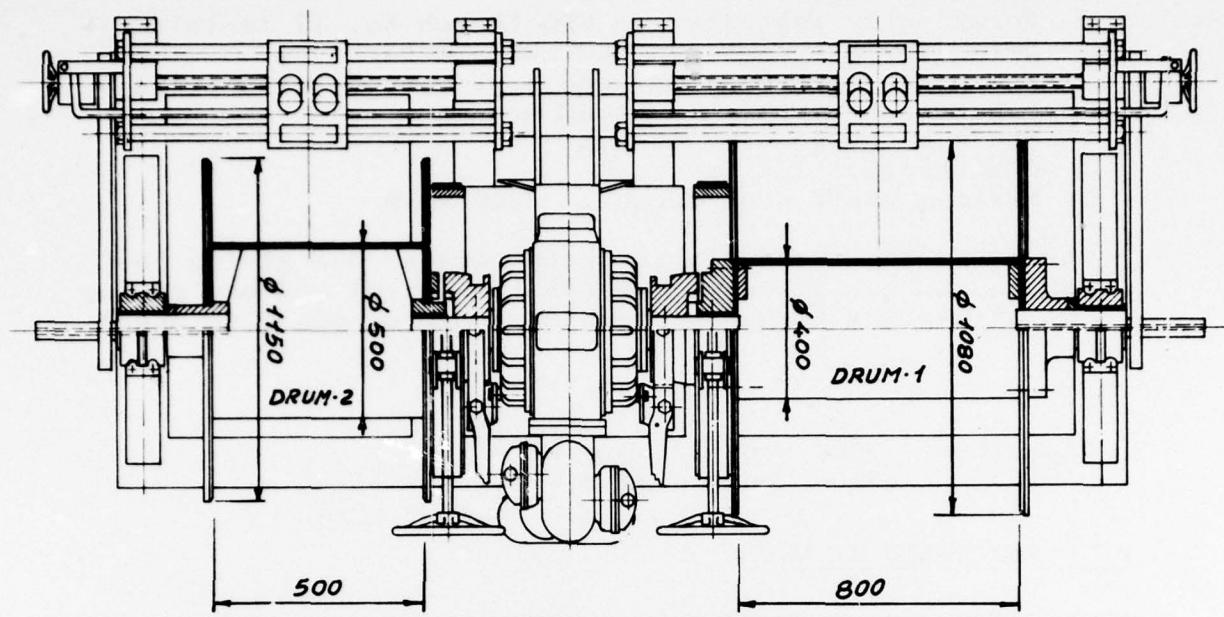
PULL AND SPEED AT DRUM

D R U M	1st Step		2nd Step	
	Pull	Speed	Pull	Speed
312 mm Ø	20400 kg	12.5 m/min	8050 kg	25 m/min
500 mm Ø	12600 kg	20 m/min	5000 kg	40 m/min
708 mm Ø	9000 kg	28.3 m/min	3540 kg	56.6 m/min
1104 mm Ø	5750 kg	44 m/min	2270 kg	88 m/min

The speed is continuously variable within the above ranges.

EQUIPMENT

- Band brake - Holding capacity is twice the maximum pull
- Spooling gear: Automatically operated, adjustable to accept both 12 and 19 mm Ø wire rope.



2. WINCH FOR T.D.S. AND TRANSDUCER SYSTEM

- Norwinch - cable-winches type - interchangeable - double drums
- Permanently installed on MPG (hatch No. 2) in 1964
- Driven by a type M-140 hydraulic motor
- The power unit utilizes a 85 h.p. a.c. motor driving a Norwinch type P 37 hydraulic pump
- Power required by the motor winch: 38 h.p.
- Shaft motor power: 28 h.p.
- Maximum shaft motor torque: 560 kg.m

The motor has two variable speed ranges, one giving the maximum torque at normal speeds (1st step) and one giving 40% of maximum torque at double normal speeds (2nd step).

- Motor with single shaft; the two drums are joined to the motor shaft by a claw coupling

DRUMS

Capacity: Drum I 5000 m of 10 mm \varnothing cable
 Drum II 6000 m of 6.35 mm \varnothing cable

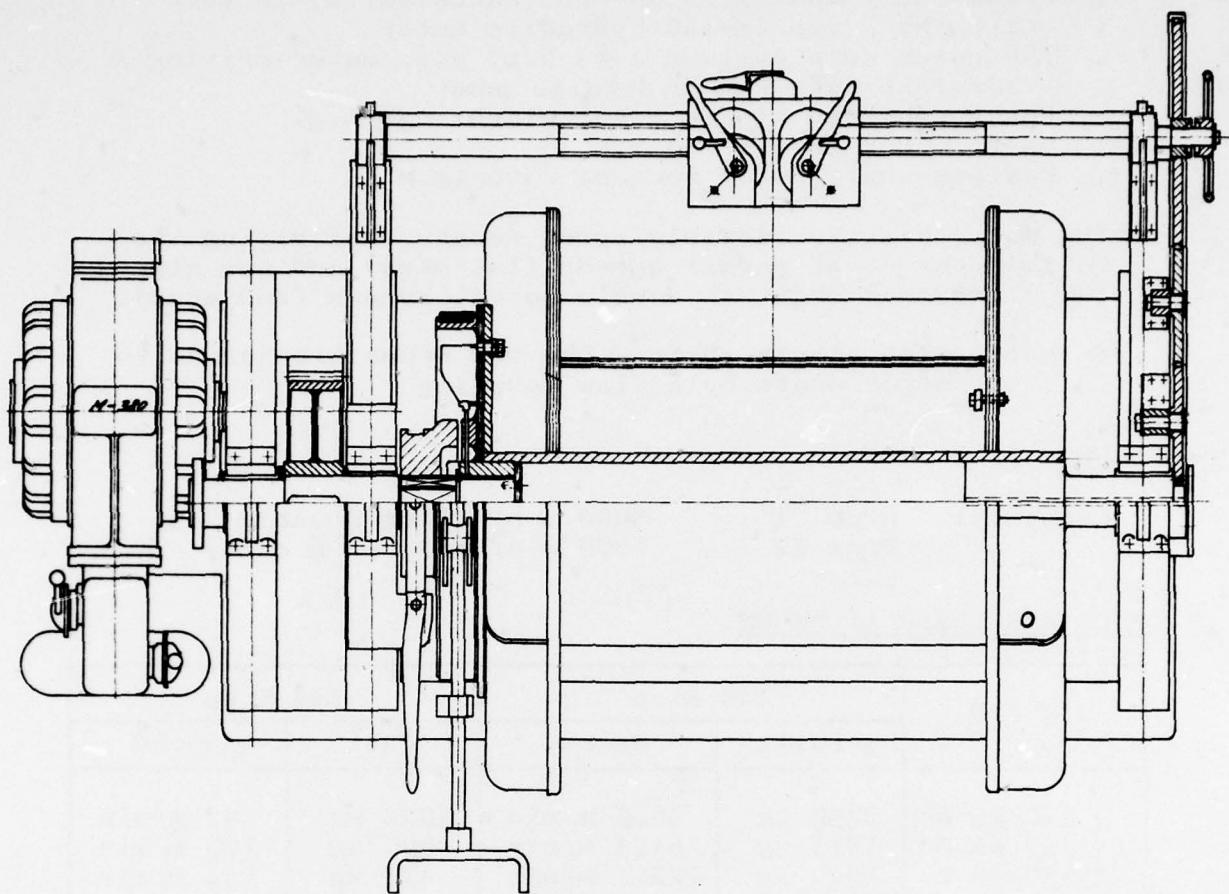
PULL AND SPEED AT DRUMS

D R U M	1st Step		2nd Step	
	Pull	Speed	Pull	Speed
I { 410 mm \varnothing	2730 kg	46.5 m/min	1092 kg	93 m/min
	1515 kg	81.5 m/min	600 kg	103 m/min
	1040 kg	122 m/min	415 kg	244 m/min
II { 510 mm \varnothing	2200 kg	57.5 m/min	880 kg	115 m/min
	1515 kg	83.5 m/min	600 kg	167 m/min
	1145 kg	111 m/min	450 kg	222 m/min

Speeds are continuously variable within the above ranges.

EQUIPMENT

- Each drum is equipped with a band brake - Holding capacity is twice the maximum pull
- Spooling gear: Each drum has an ALMEK spooling gear adjustable to accept from 4 to 30 mm \varnothing cable.



3. WINCH FOR CORER, MEDUSA AND HYDROPHONE ARRAY

- Norwinch type 9 (modified) with four interchangeable drums
- Permanently installed on MPG (foreward deck port) in 1968
- Driven by a type M-540 hydraulic motor
- The power unit utilizes a 85 h.p. a.c. motor driving a Norwinch type P 37 hydraulic motor
- Shaft motor power: 60 h.p.
- Gear ratio: 1:2.2
- Maximum shaft drum torque: 2900 kg.m

The motor has two variable speed ranges, one giving the maximum torque at normal speeds (1st step) and one giving 40% of maximum torque at double normal speeds (2nd step).

DRUMS

Capacities

I	Grooved Drum	4500 m of 19 mm Ø cable	(D.V.A.)
II	Drum	7000 m of 12 mm Ø wire	(CORER)
III	Grooved Drum	1500 m of 19 mm Ø cable	(D.S.L.)
IV	Grooved Drum	2500 m of 17 mm Ø cable	(MEDUSA)

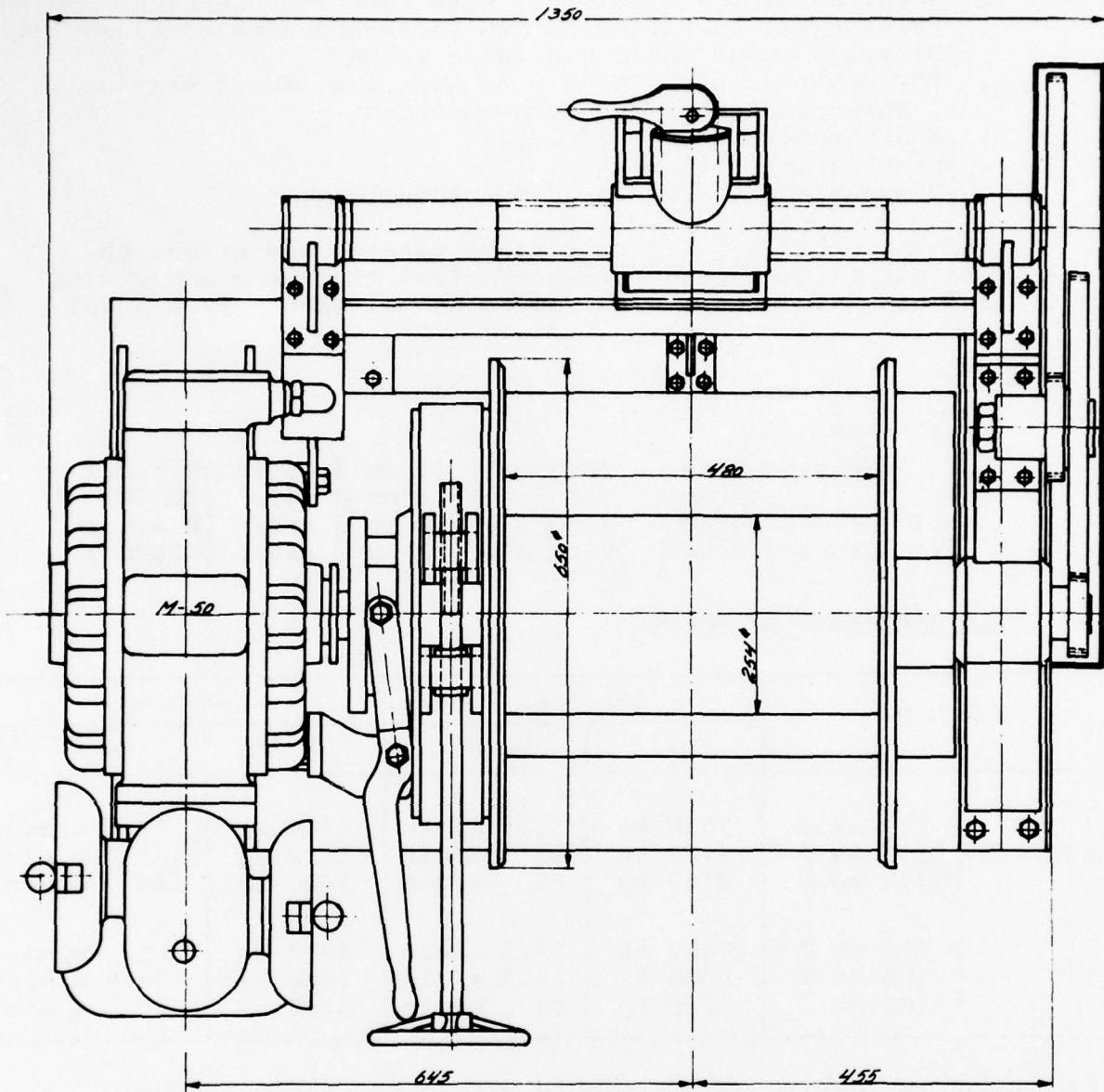
PULL AND SPEED AT DRUMS

D R U M	1st Step		2nd Step	
	Pull	Speed	Pull	Speed
I-III-IV {	898 mm Ø	7050 kg	35.8 m/min	2800 kg
	1348 mm Ø	4720 kg	54 m/min	1860 kg
	1798 mm Ø	3540 kg	72 m/min	1400 kg
II {	312 mm Ø	20400 kg	12.5 m/min	8050 kg
	708 mm Ø	9000 kg	28.3 m/min	3540 kg
	1104 mm Ø	5750 kg	44 m/min	2270 kg
			71.6 m/min	108 m/min
			144 m/min	
			25 m/min	56.6 m/min
			88 m/min	

The speed is continuously variable within the above ranges.

EQUIPMENT

- Band brake - Holding capacity is twice the maximum pull
- Spooling gear: Automatically operated, adjustable to accept 19 mm Ø, 17 mm Ø cable and 12 mm Ø wire.



4. WINCH FOR WATER SAMPLER

- Norwinch type V hydrographic winch
- Single drum
- Permanently installed on MPG (midships, starboard) in 1964
- Driven by a type M-50 hydraulic motor
- The power unit utilizes a 25 h.p. a.c. motor driving a Norwinch type P 09 hydraulic pump
- Shaft motor power: 18 h.p.
- Maximum shaft drum torque: 200 kg.m

The motor has two variable speed ranges, one giving the maximum torque at normal speeds (1st step) and one giving 25% of maximum torque at double normal speeds (2nd step).

DRUM

Capacity: 6000 m of 4 mm Ø wire

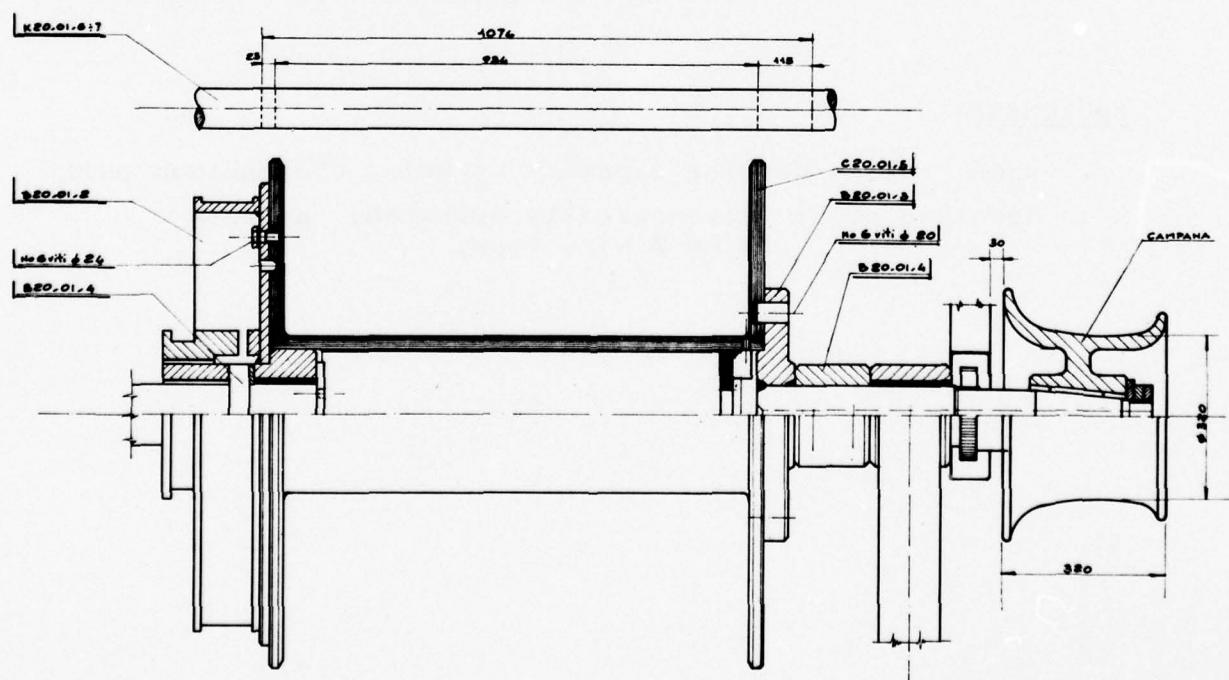
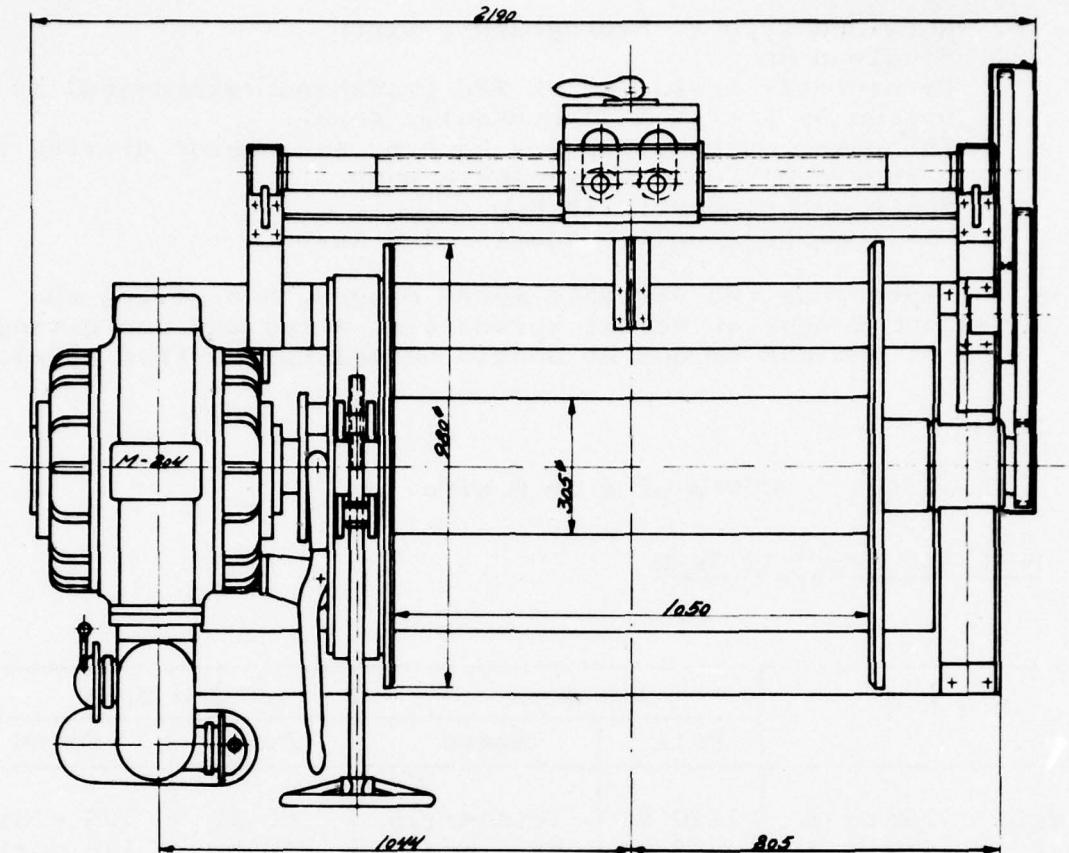
PULL AND SPEED AT DRUM

D R U M	1st Step		2nd Step	
	Pull	Speed	Pull	Speed
Empty	258 mm Ø	1550 kg	52.5 m/min	390 kg
Mid	410 mm Ø	975 kg	84 m/min	240 kg
Full	562 mm Ø	710 kg	115 m/min	180 kg
				105 m/min
				168 m/min
				230 m/min

The speed is continuously variable within the above ranges.

EQUIPMENT

- Band brake - Holding capacity is twice the maximum pull
- Spooling gear: Automatically operated; accepts 4 mm Ø wire rope.



5. WINCH FOR CORER AND TOWED EQUIPMENT

- Norwinch type IV hydrographic winch - bought in 1964
- Single drum
- Modified for interchangeable drums in 1974
- Permanently installed on MPG (stern) in 1968
- Driven by a type M-204 hydraulic motor
- The power unit utilizes a 48 h.p. a.c. motor driving a Norwinch type P 17 hydraulic pump
- Shaft motor power: 34 h.p.
- Maximum shaft drum torque: 816 kg.m

The motor has two variable speed ranges, one giving the maximum torque at normal speeds (1st step) and one giving 40% of maximum torque at double normal speeds (2nd step).

DRUM

Capacity: 4000 m of 10 mm Ø wire
 3000 m of 12 mm Ø wire
 1100 m of 19 mm Ø wire

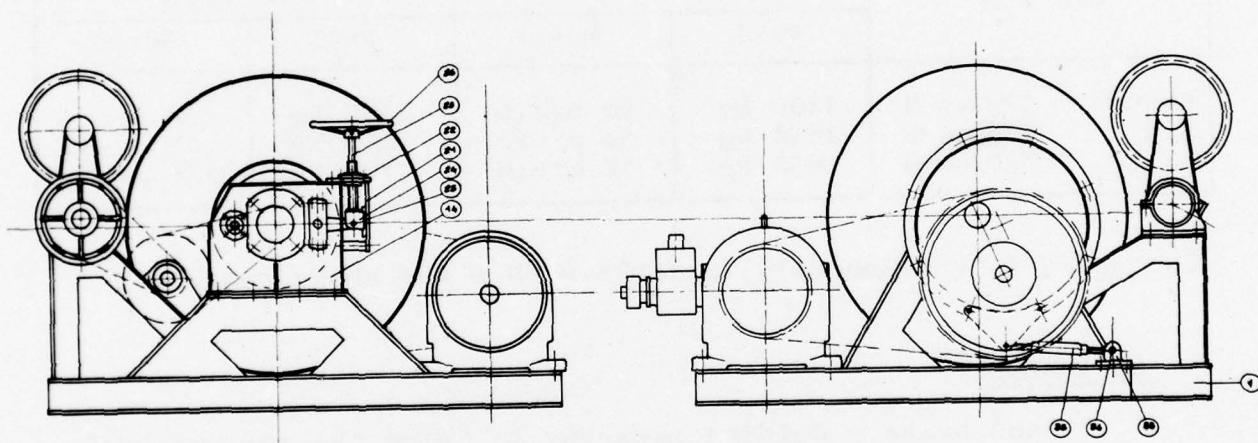
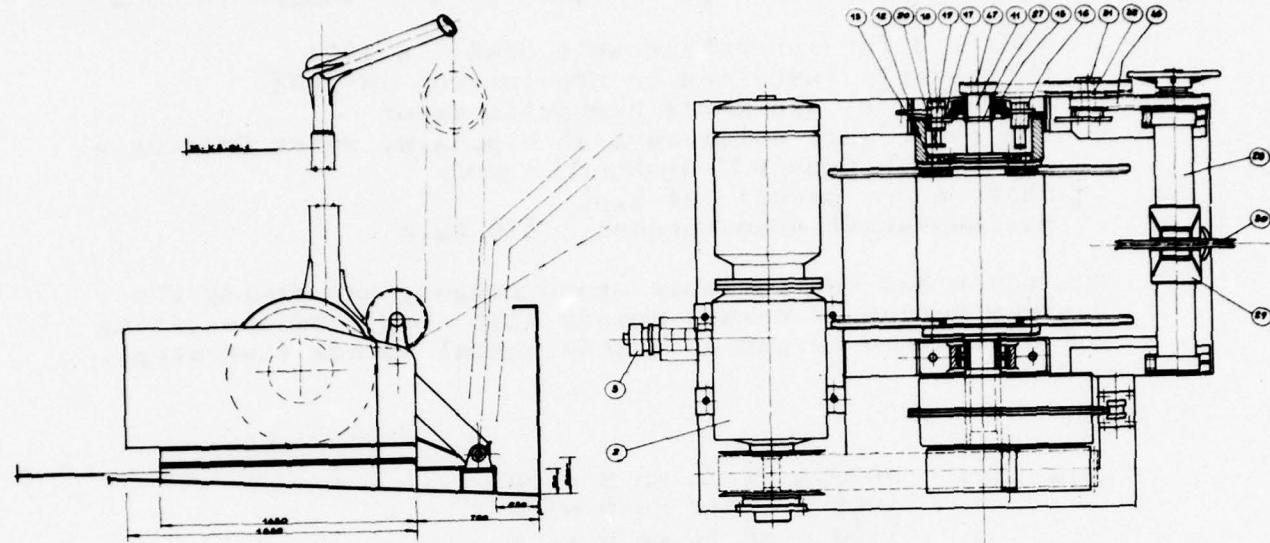
PULL AND SPEED AT DRUM

D R U M	1st Step		2nd Step	
	Pull	Speed	Pull	Speed
Empty	315 mm Ø	5200 kg	30 m/min	1900 kg
Mid	575 mm Ø	2850 kg	54 m/min	1050 kg
Full	830 mm Ø	1950 kg	78 m/min	720 kg

The speed is continuously variable within the above ranges.

EQUIPMENT

- Band brake - Holding capacity is twice the maximum pull
- Spooling gear: Automatically operated; accepts 12 mm Ø wire rope.



6. WINCH FOR SALINITY TEMPERATURE DEPTH (S.T.D.) PROBE

- Designed and built by SACLANTCEN in 1974
- Single drum
- Can be installed on MPG in one of two midship positions (port or starboard) when required
- Works in conjunction with a davit (No. 24)
- Driven by an electro-hydraulic unit utilizing a 12.5 h.p. a.c. motor
- Hydrostatic speed changer - shaft motor power: 9.5 h.p.
- Gear ratio: 27.75:1
- Maximum shaft drum torque: 220 kg.m (minimum speed)
- Work shaft drum torque: 110 kg.m (maximum speed)

DRUM

Grooved drum

Capacity: 3000 m of 6.32 mm Ø wire (cable)

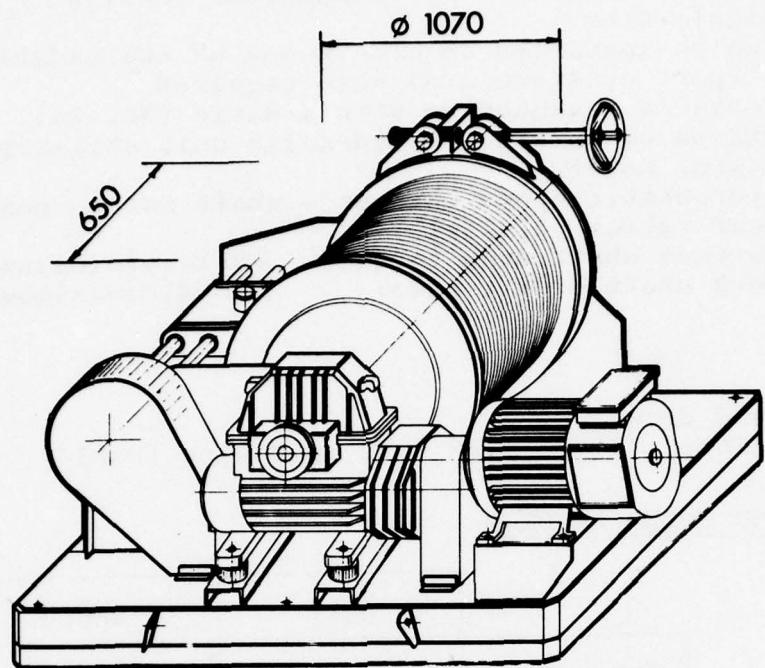
PULL AND SPEED AT DRUM

	Pull	Speed
Maximum	1000 kg	minimum
Working	500 kg	maximum

Can automatically maintain (\pm 5%) any speed between 1.2 m/min and 120 m/min.

EQUIPMENT

- Remote control
- Electromagnetic brake (operating brake) - Holding capacity is equal to maximum pull
- Block brake (emergency brake) - Holding capacity is twice the maximum pull
- Spooling gear: Automatically operated; accepts 6.35 mm Ø cable
- Electric power supply - 10 kW 208/117 V a.c. 60 Hz.



7-8. WINCHES FOR HORIZONTAL ARRAY

- LEBUS - Especially designed for SACLANTCEN (1974)
- Fixed drum
- Two can be installed on MPG (forward deck, port) when required
- Work in conjunction with davits (Nos. 22 & 23)
- Each winch is driven by a 10 h.p. d.c. motor
- Gear ratio: 176.5:1
- Maximum shaft drum torque: 430 kg.m

DRUM

Grooved drum

Capacity: 1100 m of 18 mm Ø cable

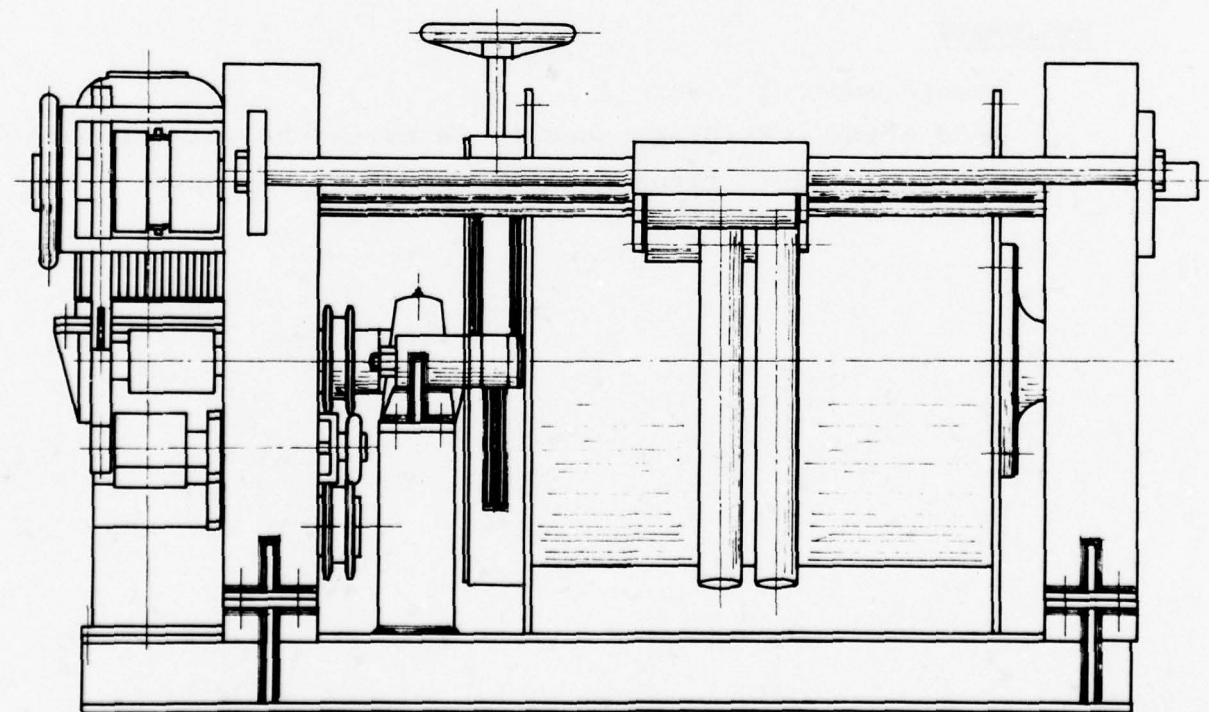
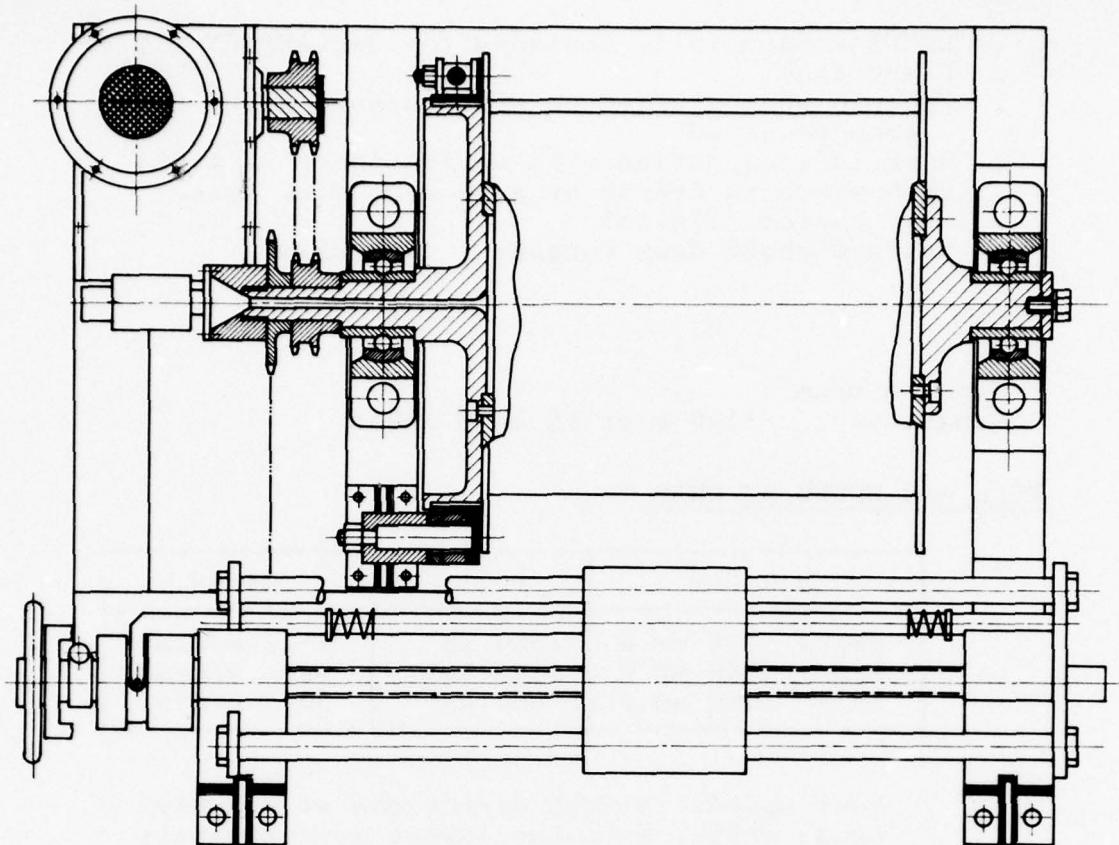
PULL AND SPEED AT DRUM

D R U M	Pull	Speed
Empty 518 mm Ø	1800 kg	15.3 m/min
Mid 750 mm Ø	1145 kg	22 m/min
Full 1000 mm Ø	860 kg	30 m/min

Four speeds in both directions at roughly equal steps, with the lowest approximately 1/8 of the highest.

EQUIPMENT

- Remote control
- Band brake - Holding capacity is twice the maximum pull
- Spooling gear: Automatically operated; accepts 18 mm Ø cable.



9. WINCH FOR TOWED FISH

- Designed and built by SACLANTCEN in 1974
- Single drum
- Can be installed on MPG (stern) when required
- Driven by an electro-hydraulic unit utilizing a 5.5 h.p. a.c. motor
- Hydrostatic speed changer
- Shaft motor power: 4.5 h.p.
- Gear ratio: 1:75.6
- Maximum shaft drum torque: 330 kg.m (minimum speed)
- Work shaft drum torque: 165 kg.m (maximum speed)

DRUM

Capacity: 500 m of 9.5 mm \varnothing (3/8 in) cable

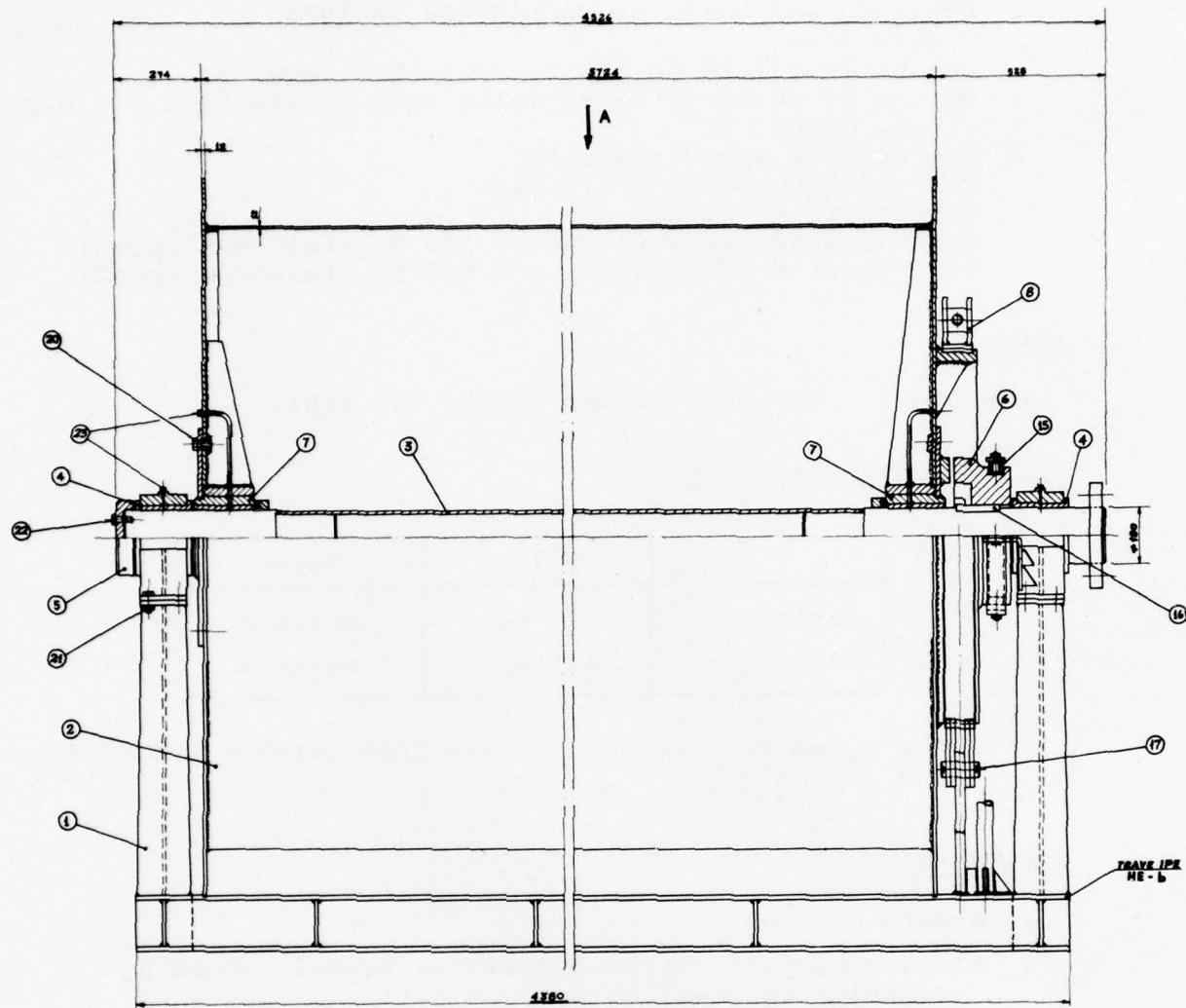
PULL AND SPEED AT DRUM

	Pull	Speed
Maximum	890 kg	minimum
Working	445 kg	maximum

The speed is continuously variable between 1.2 m/min and 35 m/min.

EQUIPMENT

- Remote control
- Electromagnetic brake (operating brake) - Holding capacity is equal to maximum pull
- Band brake (emergency brake) - Holding capacity is twice the maximum pull
- Spooling gear: Automatically operated; accepts 9.5 mm \varnothing cable.



10. WINCH FOR DEEP VERTICAL ARRAY AND SHORT VERTICAL ARRAY

- Designed by SACLANTCEN
- Built by OLMEC in 1968
- Can be installed on MPG (forward deck, port) alongside the Norwinch type 9 winch (No. 3) utilizing the same motor power by a universal joint having the same full capacity of the driven shaft.

DRUM

Capacity: 900 m of 19 mm \varnothing cable on a single layer

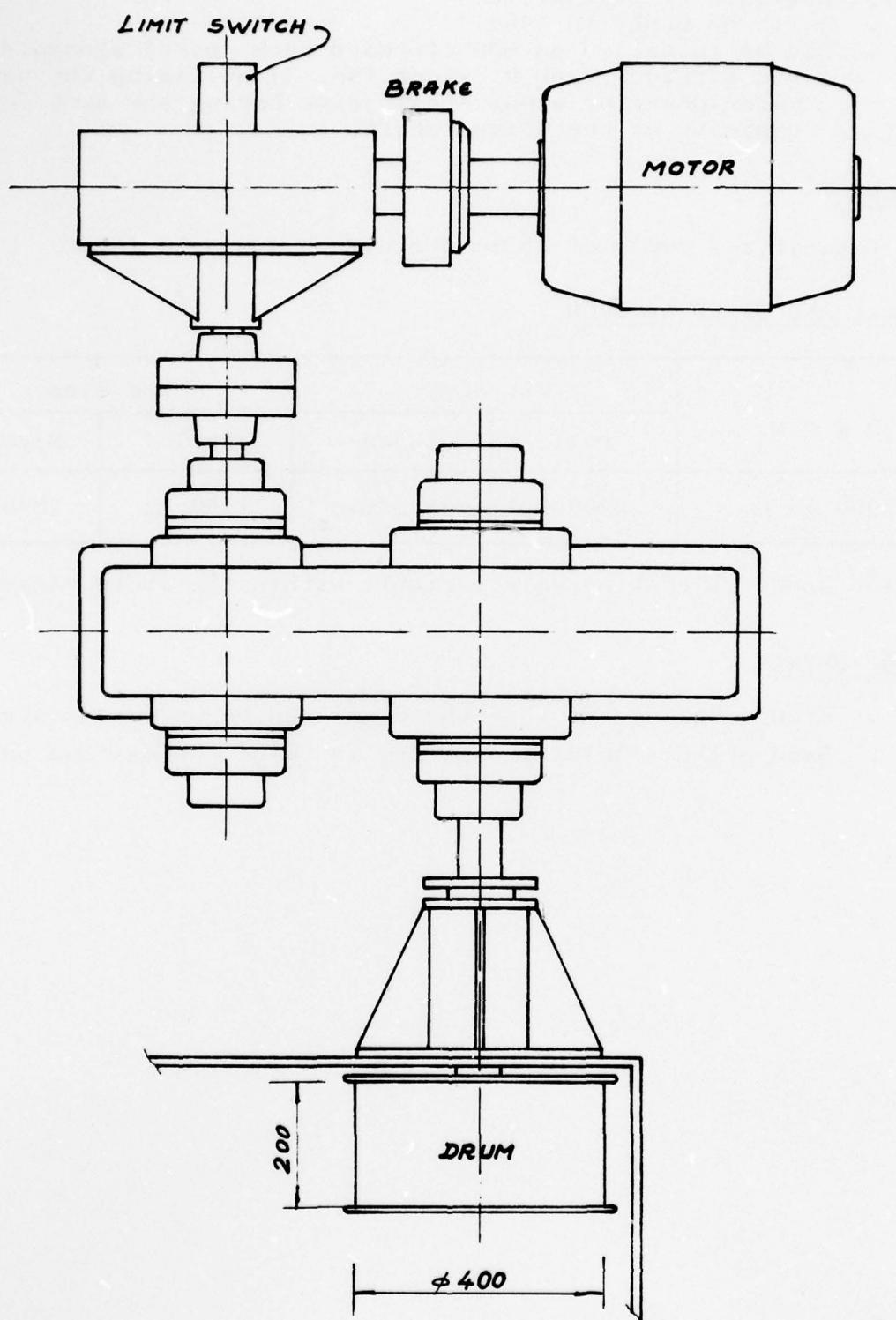
PULL AND SPEED AT DRUM

D R U M	1st Step		2nd Step	
	Pull	Speed	Pull	Speed
2000 mm \varnothing	2900 kg	35 m/min	1160 kg	70 m/min

The speed is continuously variable within the above ranges.

EQUIPMENT

- Claw coupling, so that the drums can be used separately
- Band brake - Holding capacity is twice the maximum pull.



11. WINCH FOR LIFTING THE TRANSDUCER PLATE

- SGORBINI - Especially designed for SACLANTCEN
- Permanently installed on MPG (on deck M.2) in 1964
- Driven by a 10 h.p. a.c. motor
- Gear ratio: 1:275
- Maximum shaft drun torque: 1000 kg.m

DRUM

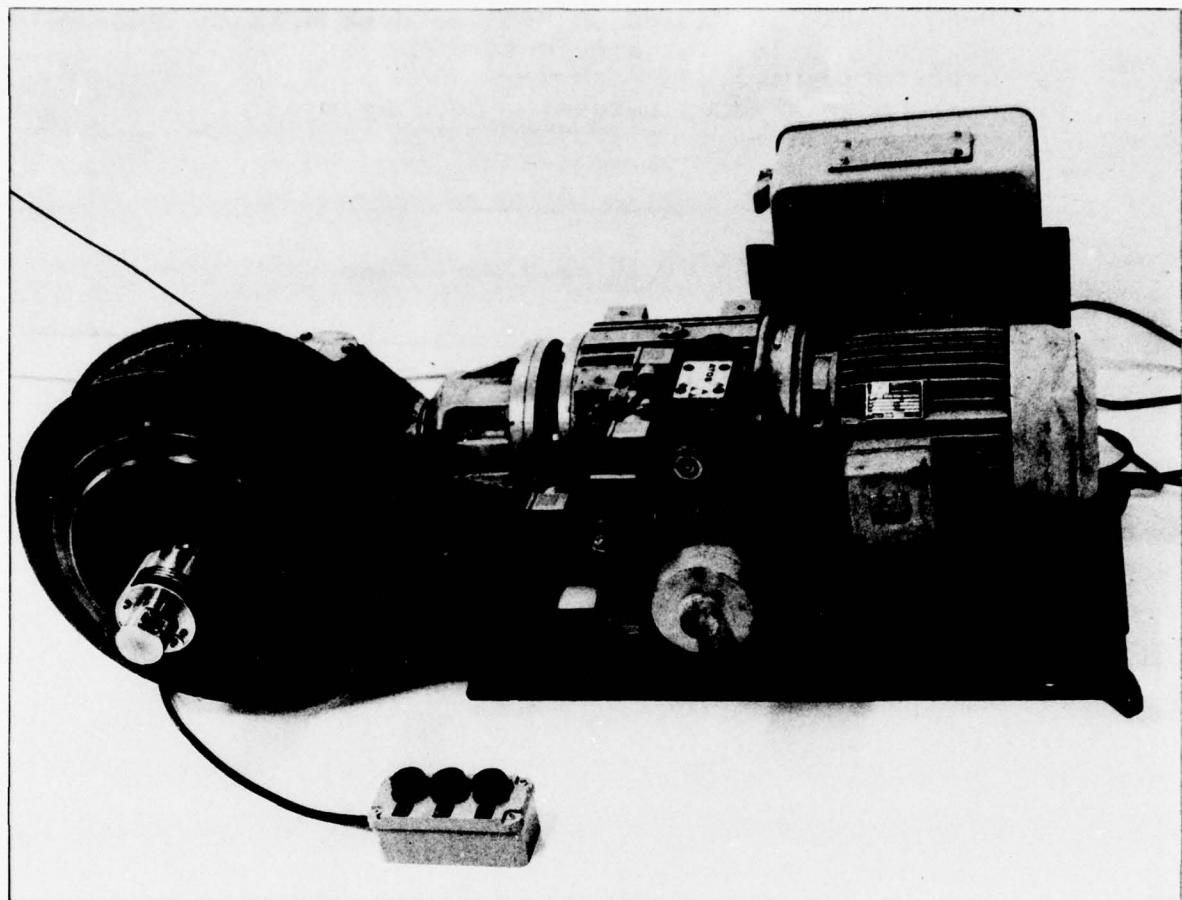
Grooved drum
Capacity: 12.5 m of 19 mm Ø wire rope

PULL AND SPEED AT DRUM

5000 kg at 5 m/min

EQUIPMENT

- Electromagnetic brake
- Limit switch



12. WINCH FOR OSCILLATING BODY

- Designed and built by SACLANTCEN in 1975
- Single drum
- Can be installed on either MPG (stern) or T-Boat (stern) when required
- Driven by an electro-hydraulic unit utilizing a 2 h.p. a.c. motor
- Hydrostatic speed changer
- Shaft motor power: 1.75 h.p.
- Gear ratio: 1:29
- Maximum shaft drum torque: 50 kg.m (minimum speed)
- Work shaft drum torque: 25 kg.m (maximum speed)

DRUM

Capacity: 500 m of 3.175 mm \varnothing (1/8 in) cable

PULL AND SPEED AT DRUM

	Pull	Speed
Maximum	250 kg	minimum
Working	125 kg	maximum

The speed is continuously variable between 1.8 m/min and 72 m/min.

EQUIPMENT

- Remote control
- Band brake - Holding capacity is twice the maximum pull.

PART 2 - LAUNCHING-AND-RECOVERY DEVICES

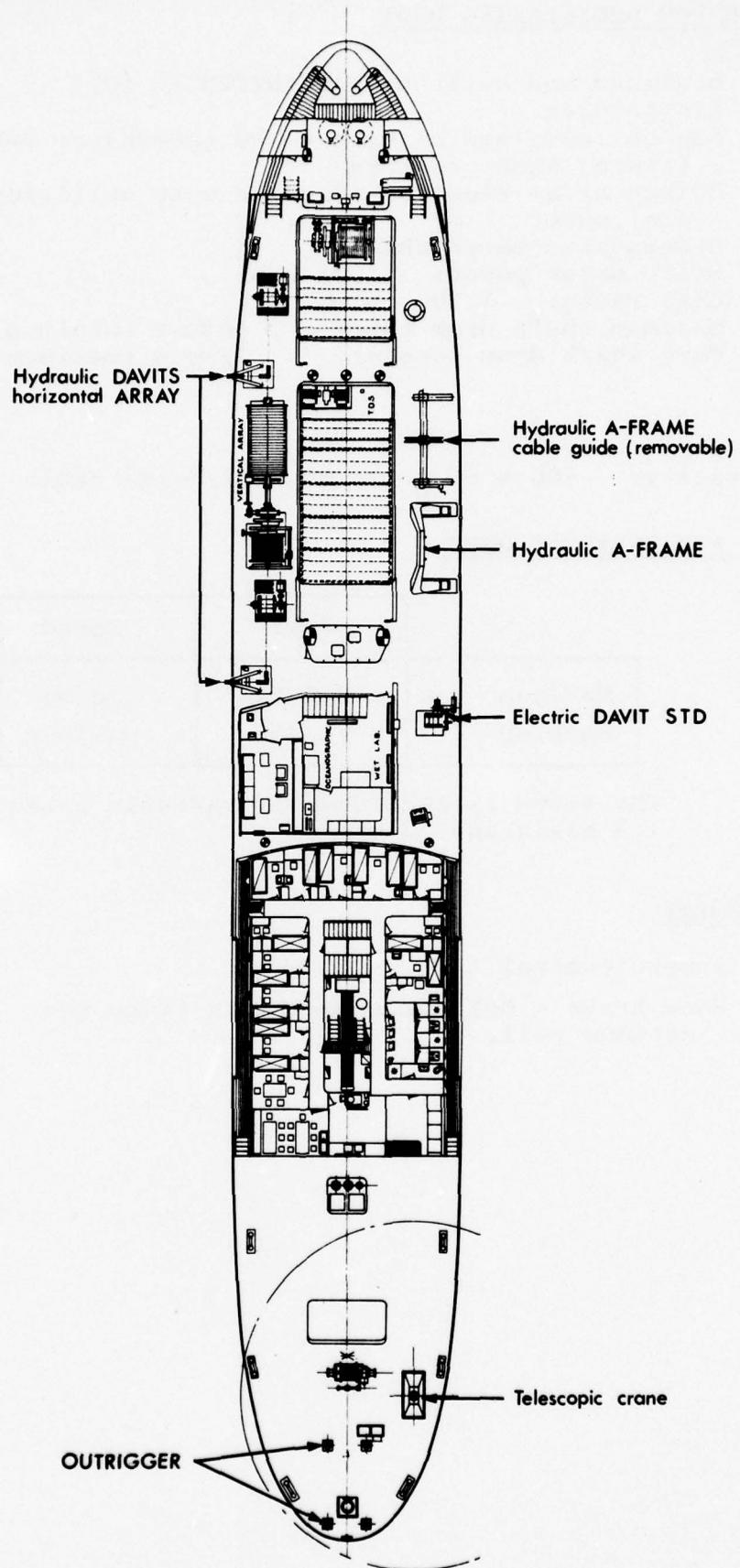
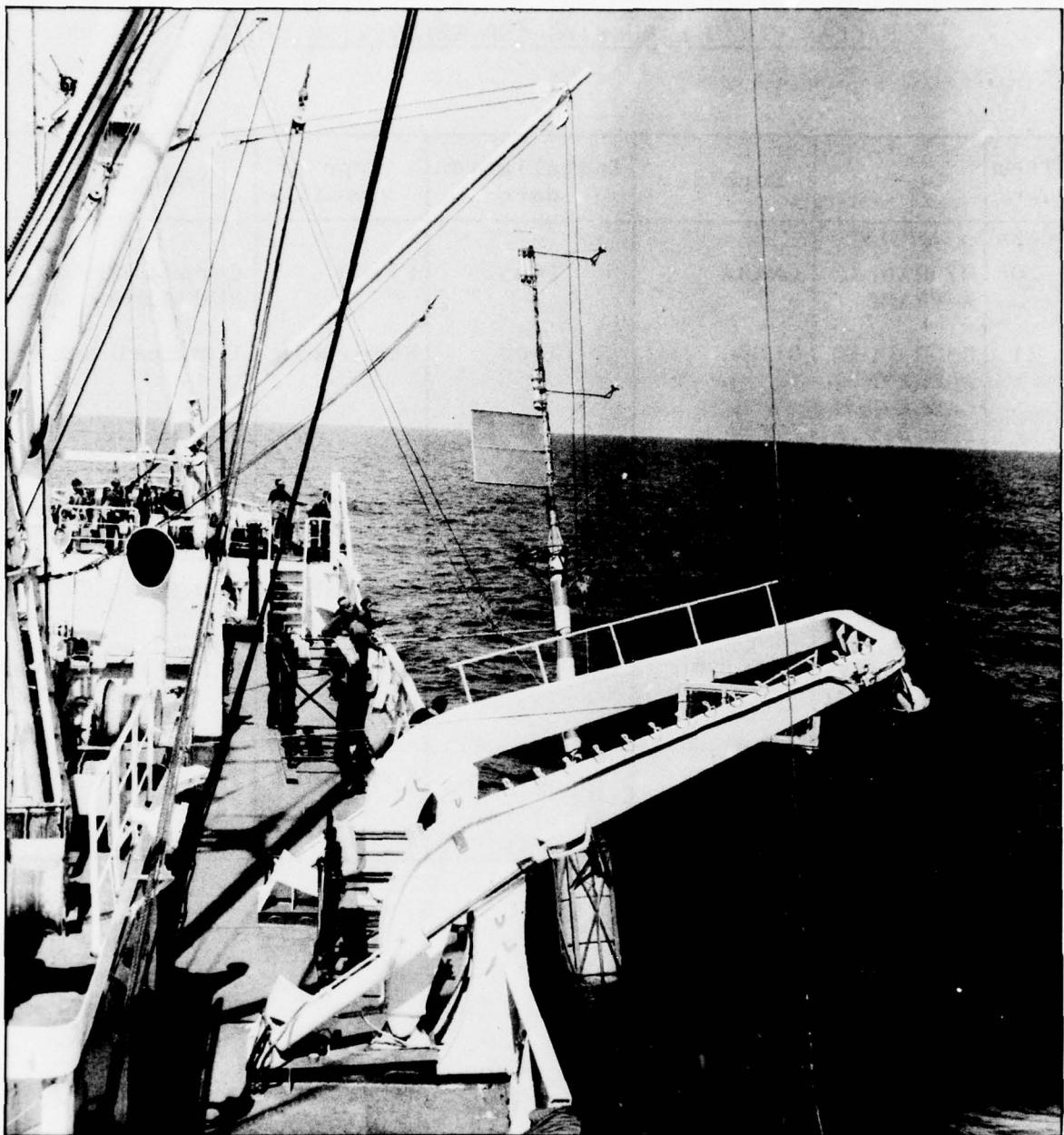


FIG. 2 POSITIONS OF LAUNCHING-AND-RECOVERY DEVICES ON MARIA PAOLINA G.

TABLE 2

SACLANTCEN'S LAUNCHING-AND-RECOVERING DEVICES

Item No.	Device	Supplier	Installation date	Type of install.	Employment
20	HYDRAULIC A-FRAME	CNASA	1965	Fixed	Corer, MEDUSA, Hydrophone array
21	HYDRAULIC A-FRAME CABLE GUIDE FOR D.V.A.	OLMEC	1968	Removable	Vertical array
22 23}	DAVITS FOR HORIZONTAL ARRAY	LEBUS	1974	Removable	Horizontal array
24	DAVIT FOR S.T.D.	SACLANTCEN	1974	Removable	T.D.S.
25	HYDRAULIC TELESCOPIC CRANE	PAGLIERO	1974	Fixed	Buoy, Transducer
26	OUTRIGGER FOR TOWED EQUIPMENT	TECMEL	1970	Removable	Towed equipment



HYDRAULIC A-FRAME

- CNASA - Especially designed for SACLANTCEN in 1965
- TECNEL - Modified in 1970
- Permanently installed on MPG (forward deck, starboard)
- Working with corer winch (No. 3) and cable winch (No. 2)
- Actuated by two hydraulic pistons, one on each side of the frame
- Powered by an oil-dynamic pump utilizing a 8 h.p. a.c. motor

INBOARD POSITION

- Deck clearance 6.5 m
- Lower width - between supports 3.35 m
- Upper width - between supports 1.6 m

OUTBOARD POSITION

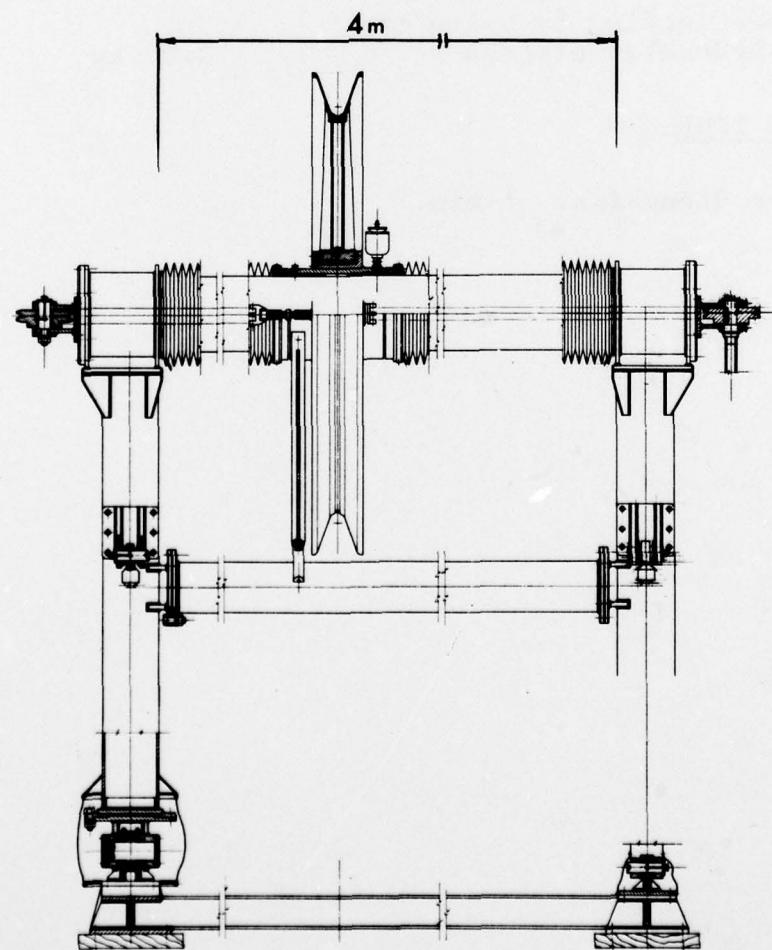
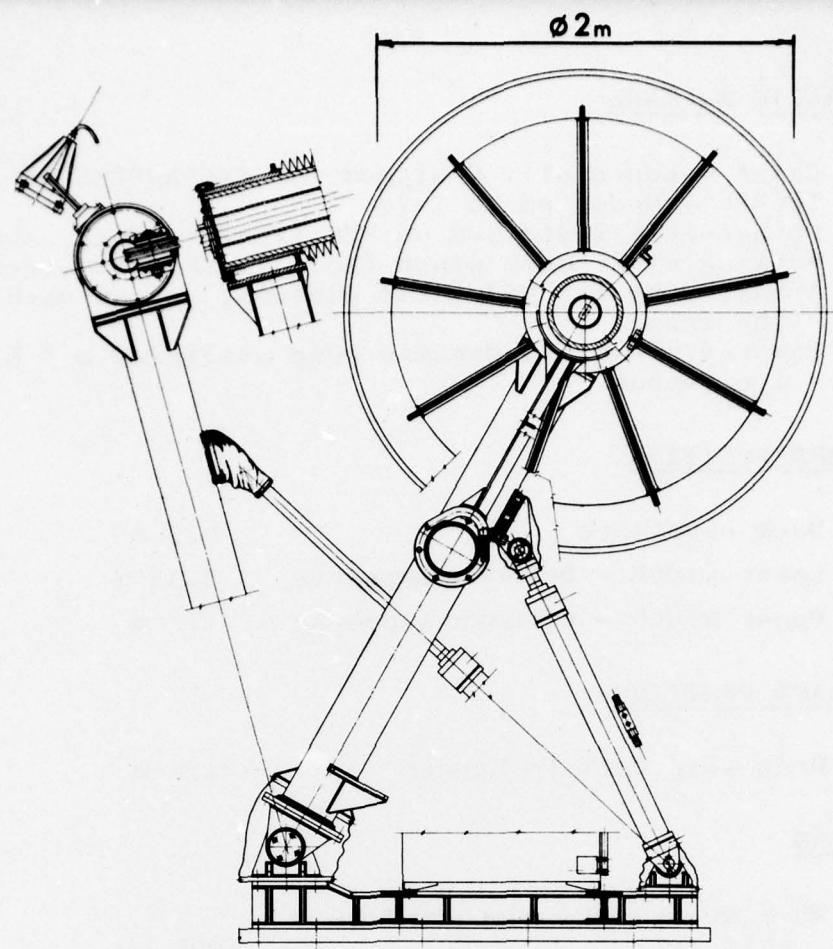
- From ship rail to hanger 4.6 m

LOADING

- When statically supported at ship rail 8000 kg
- When luffing by using the hydraulic pistons 3150 kg

LUFFING TIME

Either direction: 1 min.



21. HYDRAULIC A-FRAME - CABLE GUIDE FOR DEEP VERTICAL ARRAY

- Designed by SACLANTCEN
- Built by OLMEC in 1968
- Modified in 1970
- Can be installed on MPG (forward deck, starboard) when required
- Working with deep vertical array drum (No. 10)
- Actuated by two hydraulic pistons, one on each side of the stanchion
- Powered by an oil-dynamic pump utilizing a 12.5 h.p. a.c. motor. The sheave slides by means of a 1 h.p. a.c. motor with a 1:79.3 gear ratio.

OUTBOARD POSITION

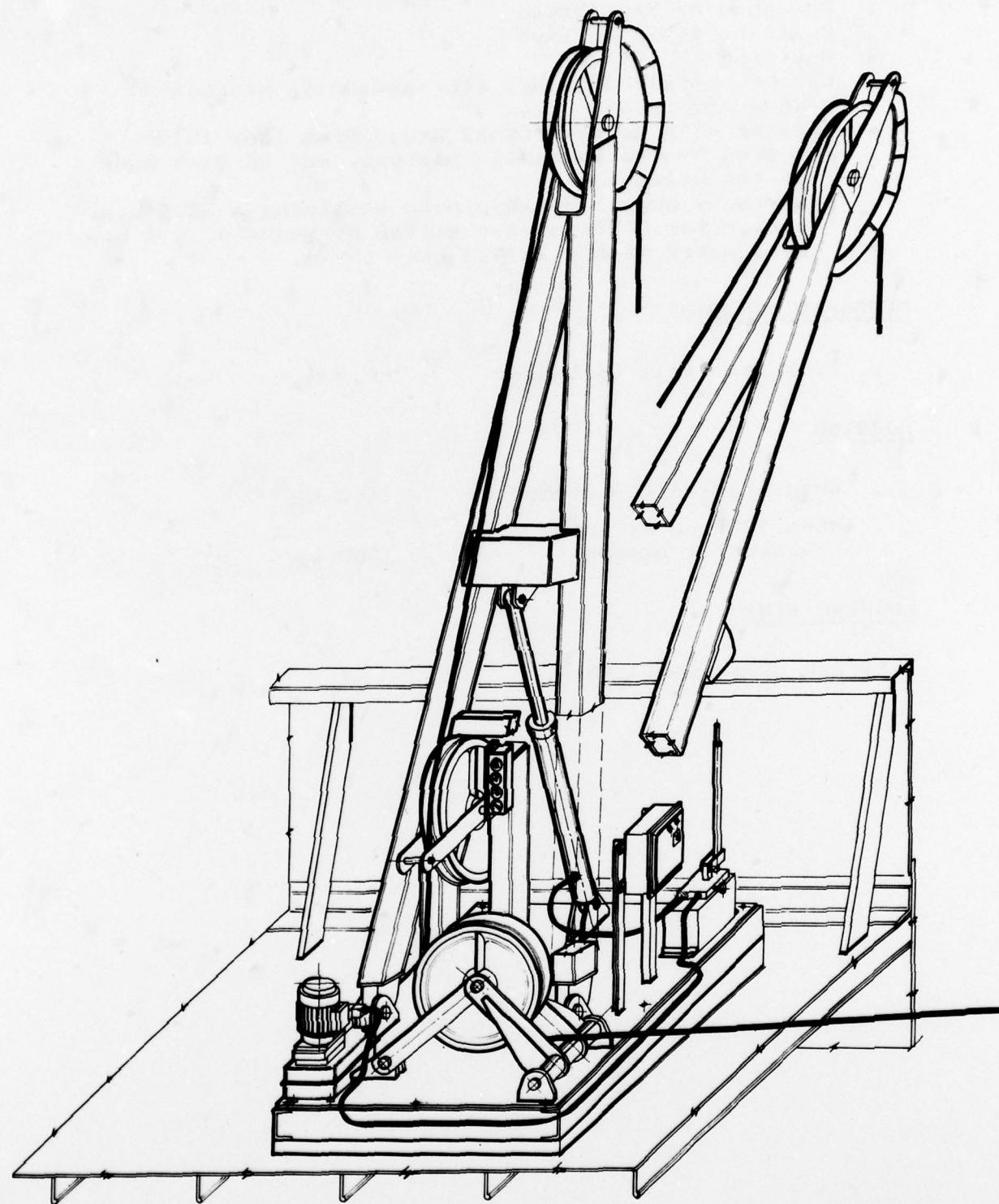
- From ship rail to hanger 0.8 m

LOADING

- When statically supported 2500 kg
- When luffing by using the hydraulic pistons 1500 kg

LUFFING TIME

Either direction: 30 s.



22-23. DAVITS FOR HORIZONTAL ARRAY

- LEBUS - Especially designed for SACLANTCEN
- Can be installed on MPG (forward deck, port) when required
- Working with LEBUS winches (Nos. 7 and 8)
- Actuated by a single hydraulic piston, powered by an oil-dynamic pump utilizing a 2 h.p. a.c. motor

OUTBOARD POSITION

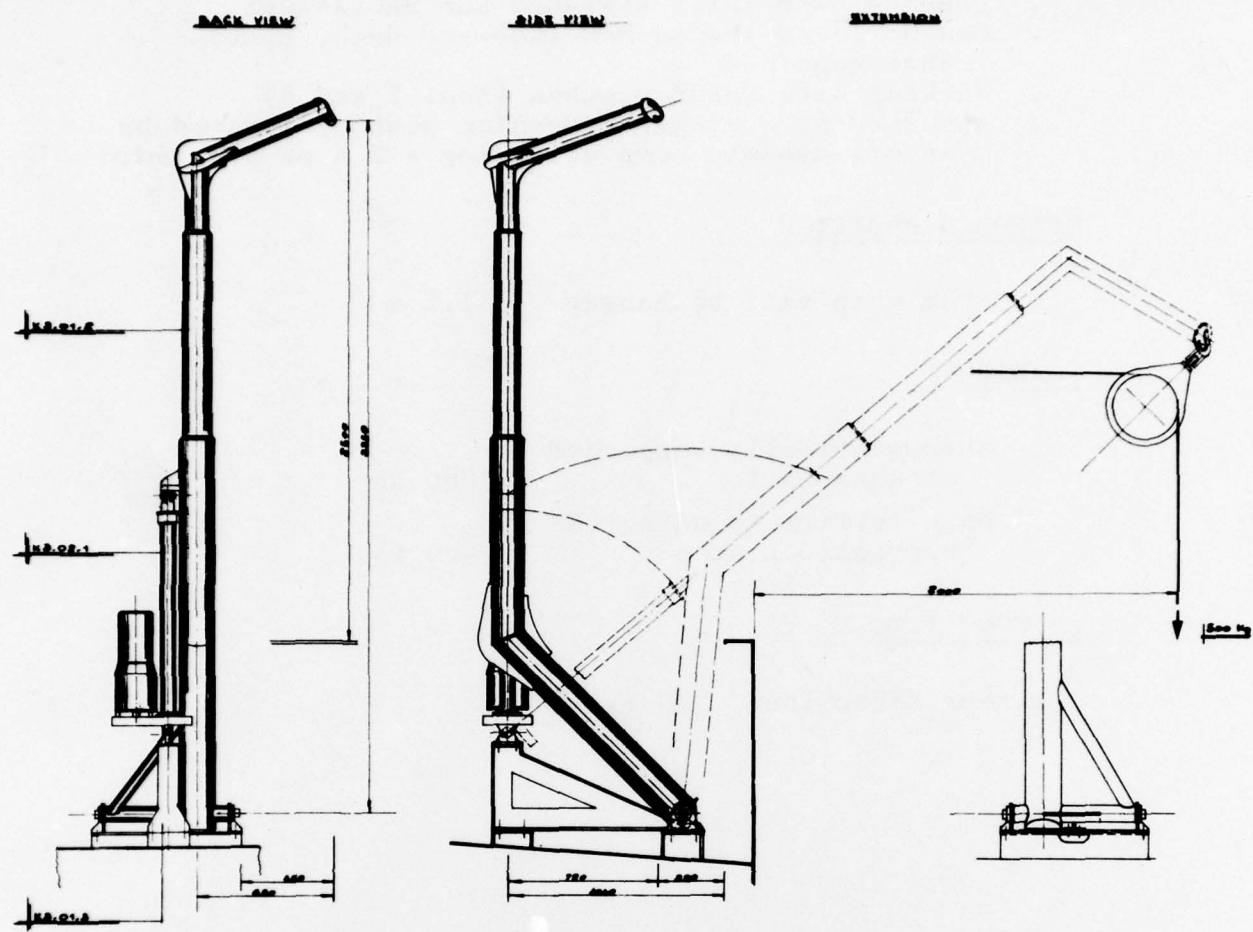
- From ship rail to hanger 1.8 m

LOADING

- When statically supported at ship rail 1800 kg
- When luffing by using the hydraulic piston 900 kg

LUFFING TIME

Either direction: 20 s.



24. DAVIT FOR S.T.D.

- Designed and built by SACLANTCEN in 1974
- Can be installed on MPG (midships starboard) on the same base as the S.T.D. winch (No. 6) and working with it
- Actuated by a servo-control
- Powered by a 2 h.p. a.c. motor

INBOARD POSITION

- Deck clearance 3.4 m

OUTBOARD POSITION

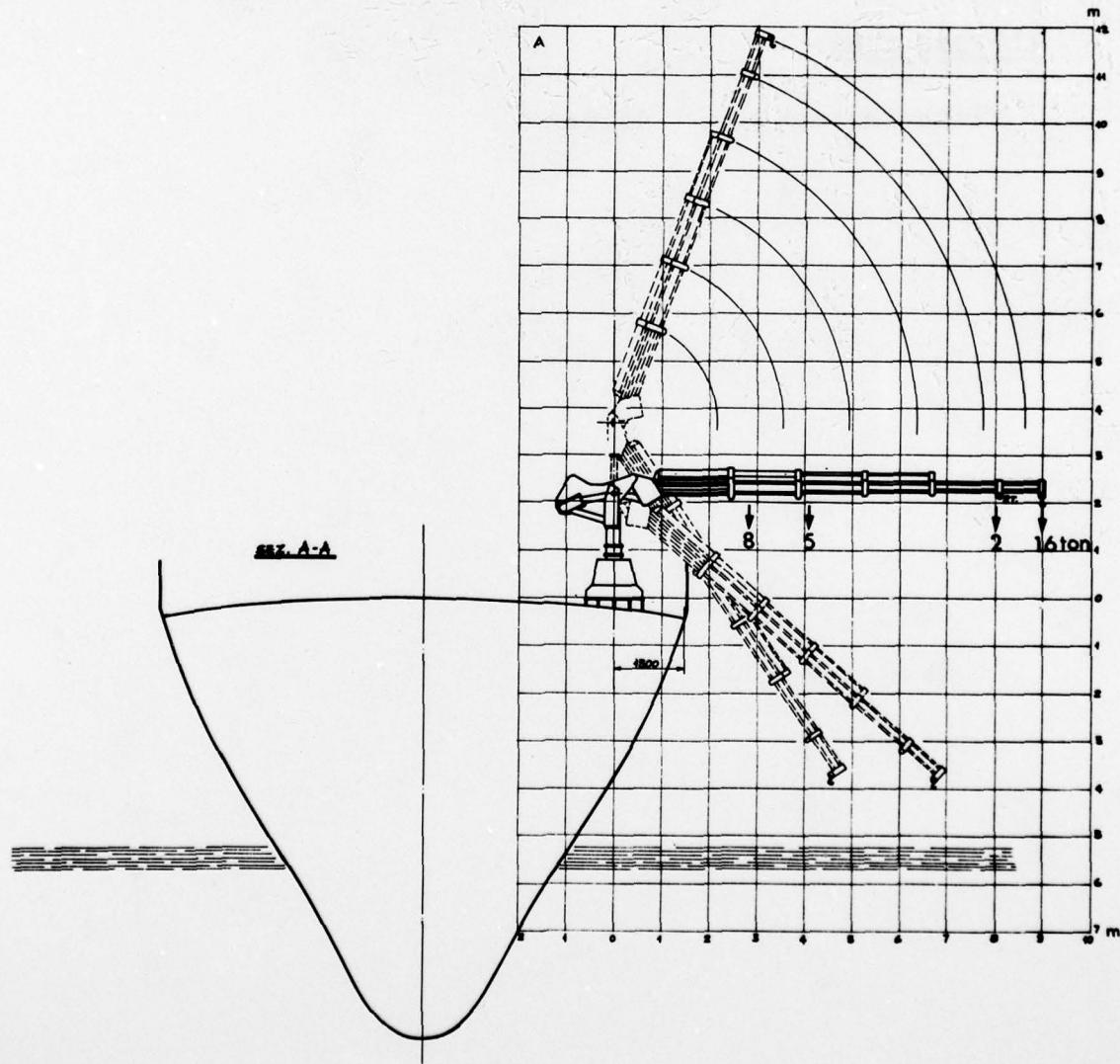
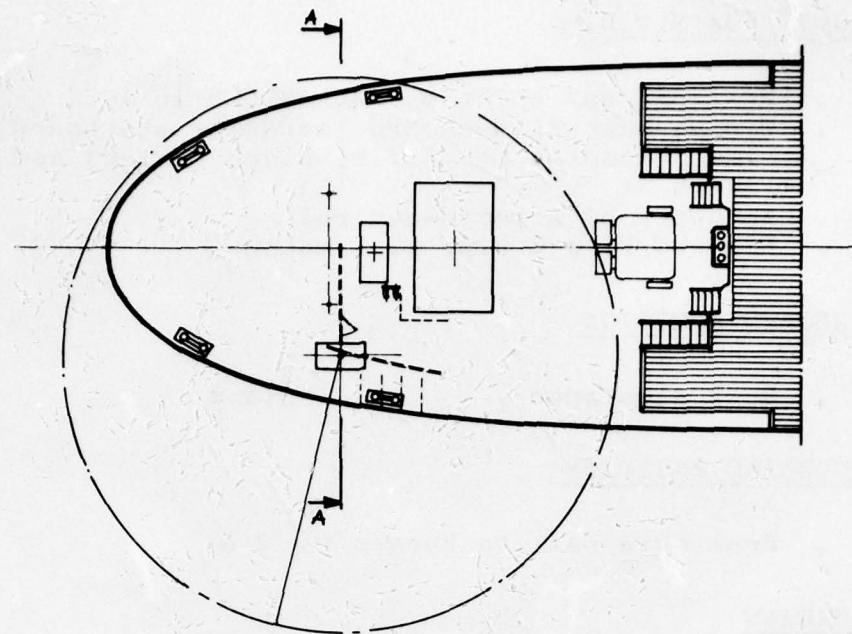
- From ship rail to hanger 2 m

LOADING

- Static or luffing 500 kg

LUFFING TIME

Either direction: 45 s.



25. HYDRAULIC TELESCOPIC CRANE

- PAGLIERO - Type OP 200L
- Permanently installed on MPG (stern)
- Used for launching and recovering oceanographic buoy, working with corer winch (No. 5), and with towed-fish winch (No. 9)
- Actuated by three hydraulic pistons for extension and elevation, by two hydraulic motor driving a double helical worm gear for rotation, and equipped with a small hydraulic winch
- Powered by an oil-dynamic pump utilizing a 20 h.p. a.c. motor

OPERATING POSITION

- Maximum extension 9 m
- Maximum elevation from deck 11 m
from sea level 15 m
- Rotation 0° to 360°

LOADING

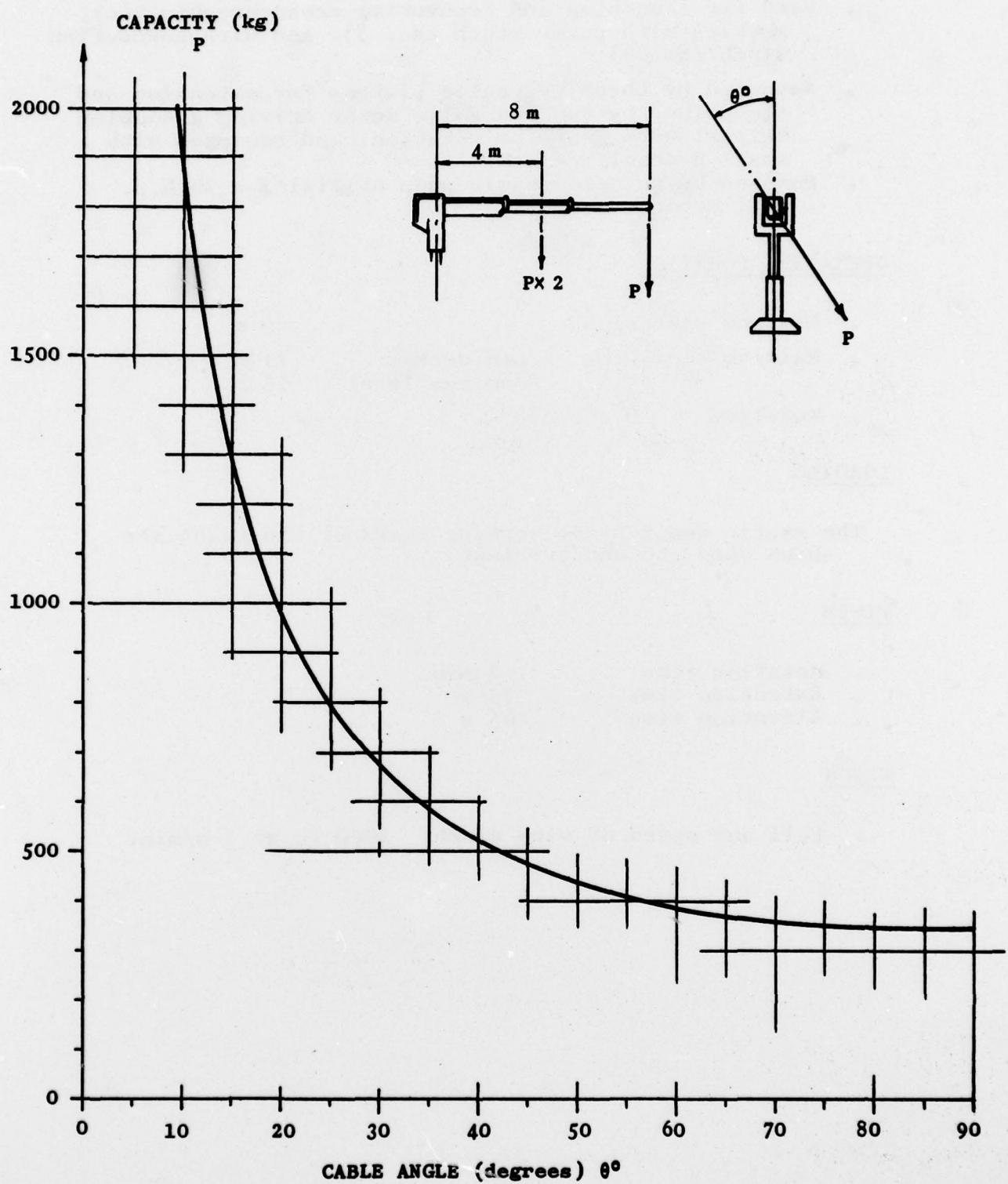
The static and dynamic working loads of the crane are shown opposite and overleaf.

TIMES

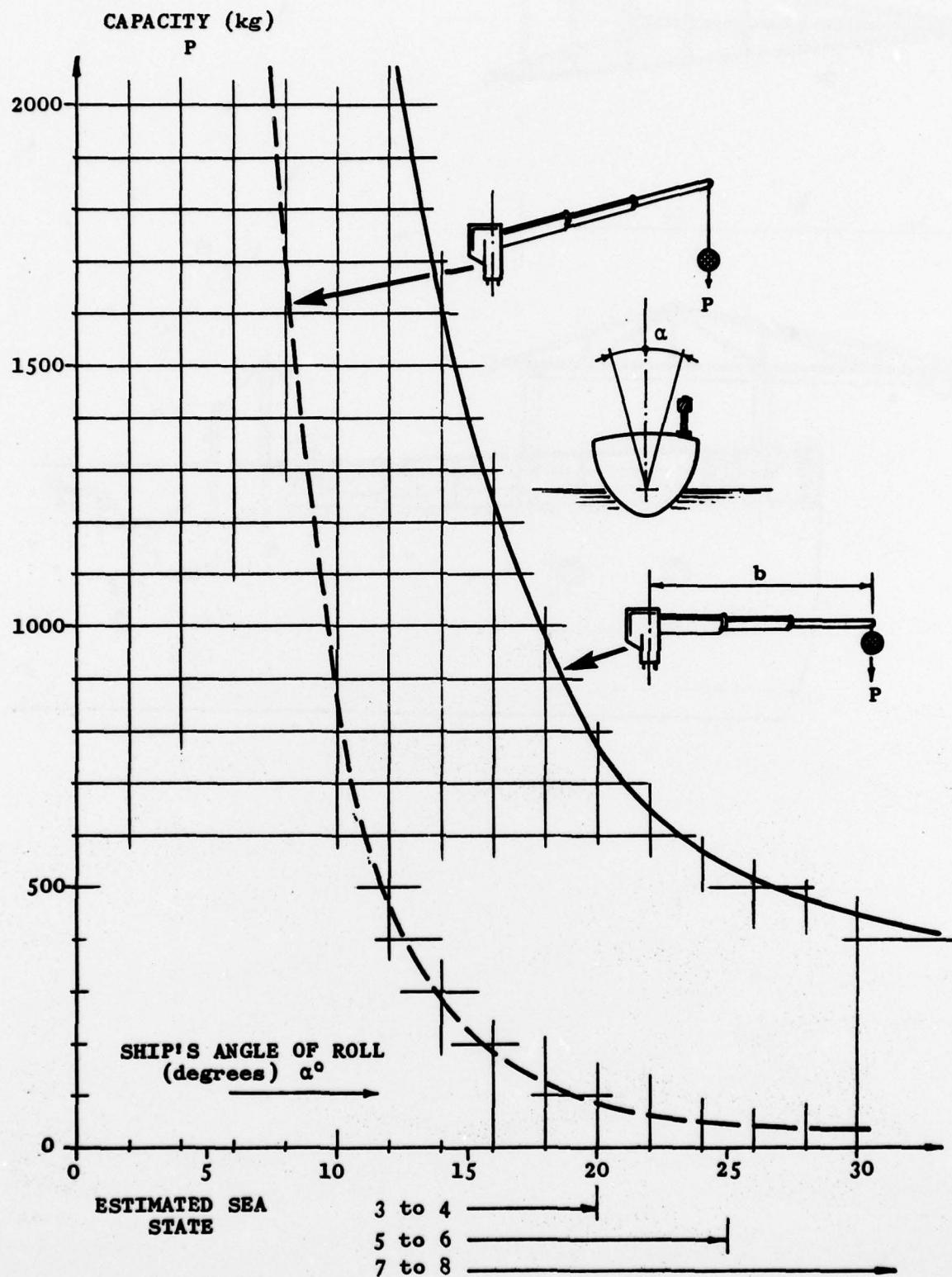
- Rotation time 2 min
- Extension time 75 s
- Elevation time 65 s

WINCH

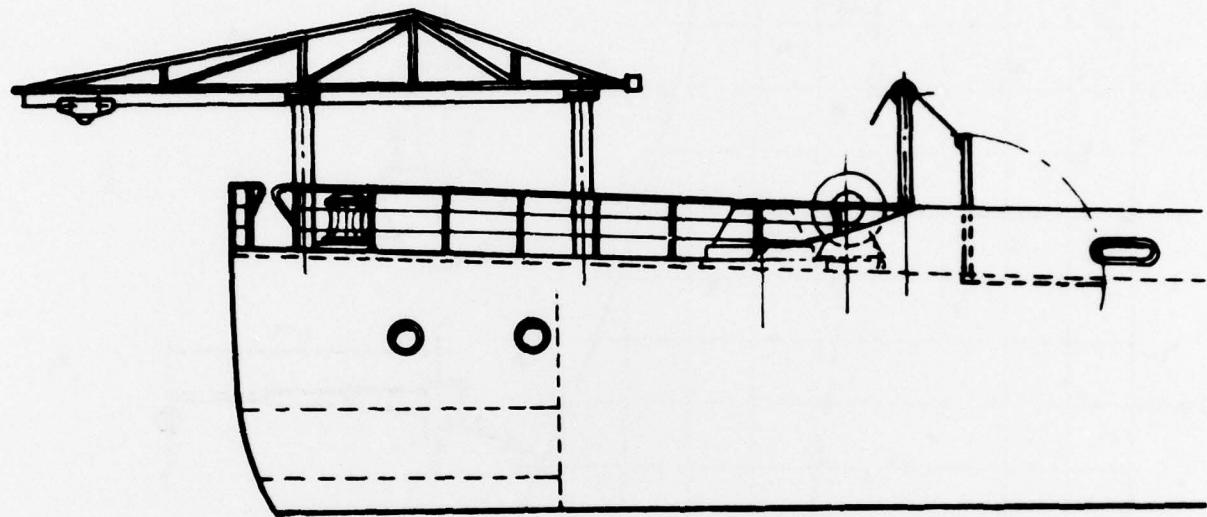
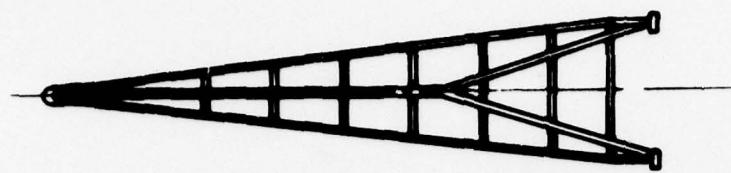
- Pull and speed of wire winch: 2000 kg at 8 m/min.



DYNAMIC WORKING LOAD OF HYDRAULIC TELESCOPIC CRANE (25):
CAPACITY AS FUNCTION OF CABLE ANGLE



DYNAMIC WORKING LOAD OF HYDRAULIC TELESCOPIC CRANE (25):
CAPACITY AS FUNCTION OF SHIP'S ROLL



26. OUTRIGGER FOR TOWED EQUIPMENT

- TECMEL - Especially designed for SACLANTCEN in 1970
- Can be installed on MPG (stern) when required
- Working with corer winch (No. 5) and towed-fish winch (No. 9)
- The hanger slides along the boom by means of a wire system driven by a 2 h.p. a.c. motor

POSITIONS

- Inboard extension from rail 5 m
- Outboard extension from rail 3 m

LOADING

- With the load statically supported 1000 kg
- With the load sliding 300 kg